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END OF SEARCH HISTORY

Key: **IEEE JNL** = IEEE Journal or Magazine, **IEE JNL** = IEE Journal or Magazine, **IEEE CNF** = IEEE Conference, **IEE CNF** = IEE Conference, **IEEE STD** = IEEE Standard

- 1. LOST: localization-space trails for robot teams**
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- 2. Augmented reality for programming industrial robots**
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- 3. Predictive robot programming**
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Volume 1, 30 Sept.-5 Oct. 2002 Page(s):876 - 881 vol.1
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- 4. Optimization of waypoint-guided potential field navigation using evolutionary algorithms**
Savage, J.; Marquez, E.; Pettersson, J.; Trygg, N.; Petersson, A.; Wahde, M.;
Intelligent Robots and Systems, 2004. (IROS 2004). Proceedings. 2004
IEEE/RSJ International Conference on
Volume 4, 28 Sept.-2 Oct. 2004 Page(s):3463 - 3468 vol.4
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- 5. Exploration of Teisi Knoll by autonomous underwater vehicle "R-One robot"**
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Volume 1, 5-8 Nov. 2001 Page(s):456 - 461 vol.1
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- 6. A multi-robot approach to stealthy navigation in the presence of an observer**
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- 7. Exploiting task regularities to transform between reference frames in robot teams**
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Volume 3, 11-15 May 2002 Page(s):2599 - 2605
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- 8. Method and system for robot end effector path correction using 3-D ultrasound sensors**
Veryba, Y.; Kourtch, L.; Verigo, B.; Murashko, V.; Intelligent Control and Automation, 2000. Proceedings of the 3rd World Congress on Volume 2, 28 June-2 July 2000 Page(s):1240 - 1243 vol.2
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- 9. Sea trials of AUV “R-One Robot” equipped with a closed cycle diesel engine system**
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- 10. Programming complex robot tasks by prediction: experimental results**
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- 11. Planning mobile sensor net deployment for navigationally-challenged sensor nodes**
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- 12. An examination of the STRIPE vehicle teleoperation system**
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- 13. Development of intelligent vehicle for waypoints navigation**
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- 14. Planning and Control of Mobile Robots in Image Space from Overhead Cameras**
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- 15. Obstacle avoidance and speed control in a mobile vehicle equipped with a compound eye**
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- 16. Choosing paths that prevent network partitioning in mobile ad-hoc networks**
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